

Math 314/814 Matrix Theory
Solutions to Exam 2 practice problems

1. Is the collection of vectors

$$\left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \in \mathbb{R}^3 : xy + z = 0 \right\}$$

a subspace of \mathbb{R}^3 ? Explain why or why not.

W is not a subspace. For example, $\vec{v} = \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} \in W$, since $(1)(1) + (-1) = 0$, but

$$2\vec{v} = \begin{bmatrix} 2 \\ 2 \\ -2 \end{bmatrix} \notin W, \text{ since } (2)(2) + (-2) = 4 - 2 = 2 \neq 0.$$

Another demonstration: $\vec{v} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ and $\vec{w} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ are both in W , but $\vec{v} + \vec{w} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$ is not in W .

2. Find a basis for \mathbb{R}^3 that **includes** the vectors $\begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}$ and $\begin{bmatrix} 1 \\ 2 \\ 5 \end{bmatrix}$.

To extend \vec{v}_1 and \vec{v}_2 to a basis for all of \mathbb{R}^3 , we can add any basis to the collection and then use row reduction to pick a basis from among the larger set. If we make sure that \vec{v}_1 and \vec{v}_2 are at the beginning of the list, row reduction will produce pivots in those columns, so we will choose those vectors. Any basis will do; we might as well choose \vec{e}_1, \vec{e}_2 , and \vec{e}_3 ! So we row reduce:

$$A = \begin{bmatrix} 2 & 1 & 1 & 0 & 0 \\ 1 & 2 & 0 & 1 & 0 \\ 1 & 5 & 0 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 0 & 1 & 0 \\ 0 & -3 & 1 & -2 & 0 \\ 0 & 3 & 0 & -1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 0 & 1 & 0 \\ 0 & 3 & 0 & -1 & 1 \\ 0 & -3 & 1 & -2 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 0 & 1 & 0 \\ 0 & 3 & 0 & -1 & 1 \\ 0 & 0 & 1 & -3 & 1 \end{bmatrix}$$

at which point we can **stop**; there are pivots in each of the first three columns. Since the last three columns span \mathbb{R}^3 , $\text{col}(A) = \mathbb{R}^3$, and the first three columns, the columns corresponding to the pivots, form a basis for $\text{col}(A) = \mathbb{R}^3$. So a basis for \mathbb{R}^3 is given by

$$\begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 5 \end{bmatrix}, \text{ and } \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}.$$

Alternatively, we could manufacture **any** vector \vec{v}_3 which does not lie in the span of \vec{v}_1 and \vec{v}_2 ; then \vec{v}_1, \vec{v}_2 and \vec{v}_3 are three linearly independent vectors in \mathbb{R}^3 , and so form a basis for \mathbb{R}^3 .

3. Find the **dimensions** of the row, column, and nullspaces of the matrix

$$B = \begin{bmatrix} 1 & -1 & 1 & 3 & -1 \\ 1 & 0 & 2 & 1 & 0 \\ 1 & 1 & 3 & 0 & 0 \\ 1 & 2 & 4 & 1 & -2 \end{bmatrix}$$

To compute the dimensions, we really only need to know how many pivots the matrix has. So we row reduce:

$$\begin{aligned} B = \begin{bmatrix} 1 & -1 & 1 & 3 & -1 \\ 1 & 0 & 2 & 1 & 0 \\ 1 & 1 & 3 & 0 & 0 \\ 1 & 2 & 4 & 1 & -2 \end{bmatrix} &\rightarrow \begin{bmatrix} 1 & 0 & 2 & 1 & 0 \\ 1 & -1 & 1 & 3 & -1 \\ 1 & 1 & 3 & 0 & 0 \\ 1 & 2 & 4 & 1 & -2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 2 & 1 & 0 \\ 0 & -1 & -1 & 2 & -1 \\ 0 & 1 & 1 & -1 & 0 \\ 0 & 2 & 2 & 0 & -2 \end{bmatrix} \rightarrow \\ &\begin{bmatrix} 1 & 0 & 2 & 1 & 0 \\ 0 & 1 & 1 & -1 & 0 \\ 0 & -1 & -1 & 2 & -1 \\ 0 & 2 & 2 & 0 & -2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 2 & 1 & 0 \\ 0 & 1 & 1 & -1 & 0 \\ 0 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 2 & -2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 2 & 1 & 0 \\ 0 & 1 & 1 & -1 & 0 \\ 0 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \end{aligned}$$

This is enough; we see that the matrix B has an REF with three pivots. Consequently, since it has five columns, it has two free variables, and

$$\dim(\text{col}(B)) = \dim(\text{row}(B)) = 3 \quad \text{and} \quad \dim(\text{null}(B)) = 2.$$

4. Find the determinant of the matrix $B = \begin{bmatrix} 3 & 1 & 0 \\ 1 & 5 & 2 \\ 0 & 1 & 3 \end{bmatrix}$.

Many methods work fine; here let's expand on the first row:

$$\begin{aligned} \det(B) &= (3) \begin{vmatrix} 5 & 2 \\ 1 & 3 \end{vmatrix} - (1) \begin{vmatrix} 1 & 2 \\ 0 & 3 \end{vmatrix} + (0) \begin{vmatrix} 1 & 5 \\ 0 & 1 \end{vmatrix} \\ &= (3)\{15 - 2\} - (1)\{3 - 0\} + (0) = 39 - 3 = 36. \end{aligned}$$

5. The matrix $A = \begin{bmatrix} -1 & 1 & 3 & -1 \\ -1 & 1 & 1 & 1 \\ -2 & 1 & 4 & -1 \\ -1 & 0 & 1 & 2 \end{bmatrix}$ has characteristic polynomial

$$\chi_A(\lambda) = (\lambda - 1)^2(\lambda - 2)^2.$$

Find the eigenvalues of A and bases for each of the corresponding eigenspaces. Is A diagonalizable? Why or why not?

The eigenvalues are the roots of $\chi_A(\lambda)$, which are $\lambda = 1, 2$. Then we row reduce:

$$A - (1)I = \begin{bmatrix} -2 & 1 & 3 & -1 \\ -1 & 0 & 1 & 1 \\ -2 & 1 & 3 & -1 \\ -1 & 0 & 1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} -1 & 0 & 1 & 1 \\ -2 & 1 & 3 & -1 \\ -2 & 1 & 3 & -1 \\ -1 & 0 & 1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -1 & -1 \\ -2 & 1 & 3 & -1 \\ -2 & 1 & 3 & -1 \\ -1 & 0 & 1 & 1 \end{bmatrix} \rightarrow$$

$$\begin{bmatrix} 1 & 0 & -1 & -1 \\ 0 & 1 & 1 & -3 \\ 0 & 1 & 1 & -3 \\ 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -1 & -1 \\ 0 & 1 & 1 & -3 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

so the last two variables z, w are free, $x = z + w$ and $y = -z + 3w$, so

$$\begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix} = \begin{bmatrix} z + w \\ -z + 3w \\ z \\ w \end{bmatrix} = z \begin{bmatrix} 1 \\ -1 \\ 1 \\ 0 \end{bmatrix} + w \begin{bmatrix} 1 \\ 3 \\ 0 \\ 1 \end{bmatrix}, \text{ and so } \begin{bmatrix} 1 \\ -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \\ 0 \\ 1 \end{bmatrix} \text{ form a basis for the}$$

$\lambda = 1$ eigenspace.

$$A - (2)I = \begin{bmatrix} -3 & 1 & 3 & -1 \\ -1 & -1 & 1 & 1 \\ -2 & 1 & 2 & -1 \\ -1 & 0 & 1 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} -1 & 0 & 1 & 0 \\ -3 & 1 & 3 & -1 \\ -1 & -1 & 1 & 1 \\ -2 & 1 & 2 & -1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -1 & 0 \\ -3 & 1 & 3 & -1 \\ -1 & -1 & 1 & 1 \\ -2 & 1 & 2 & -1 \end{bmatrix} \rightarrow$$

$$\begin{bmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & 0 & -1 \\ 0 & -1 & 0 & 1 \\ 0 & 1 & 0 & -1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

so the last two variables z, w are also free, $x = z$ and $y = -w$, so

$$\begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix} = \begin{bmatrix} z \\ w \\ z \\ w \end{bmatrix} = z \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix} + w \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix}, \text{ and so } \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix} \text{ form a basis for the } \lambda = 2$$

eigenspace.

And since the geometric multiplicity of each eigenvalue equals 2, which equals the algebraic multiplicity of each eigenvalue, the matrix A is diagonalizable!

6. Show that if $\vec{v} \neq \vec{0}$ is an eigenvector for two $n \times n$ matrices A and B , then \vec{v} is **also** an eigenvector for both of the product matrices AB and BA . Show that under these circumstances we can conclude that the matrix $AB - BA$ is **not** invertible.

We are told that $A\vec{v} = \lambda_1\vec{v}$ and $B\vec{v} = \lambda_2\vec{v}$ for some λ_1, λ_2 . So

$$AB\vec{v} = A(B\vec{v}) = A(\lambda_2\vec{v}) = \lambda_2(A\vec{v}) = \lambda_2(\lambda_1\vec{v}) = (\lambda_1\lambda_2)\vec{v}, \text{ and}$$

$$BA\vec{v} = B(A\vec{v}) = B(\lambda_1\vec{v}) = \lambda_1(B\vec{v}) = \lambda_1(\lambda_2\vec{v}) = (\lambda_1\lambda_2)\vec{v},$$

so \vec{v} is also an eigenvector for both AB and BA . But then $(AB - BA)\vec{v} = AB\vec{v} - BA\vec{v} = (\lambda_1\lambda_2)\vec{v} - (\lambda_1\lambda_2)\vec{v} = \vec{0}$, so $AB - BA$ has non-trivial nullspace, and so it cannot be invertible.